



3D Safari: Learning to Estimate Zebra Pose, Shape, and Texture from Images “In the Wild”

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The Grevy's zebra



The Grevy's zebra

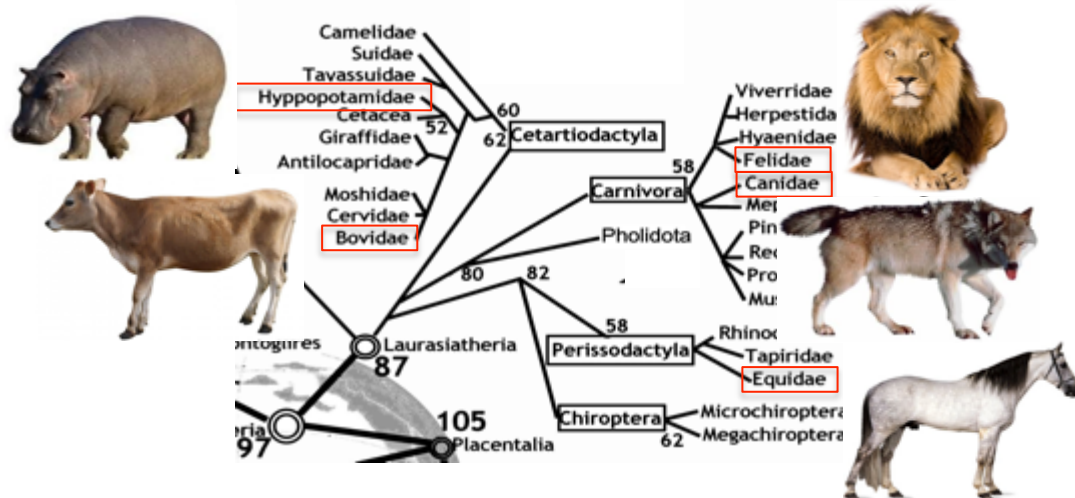


<https://zebra.wildbook.org/>
First census of the Grevy's zebra
with photographs of ordinary
citizens



SMAL

- Skinned Multi-Animal Linear model
- A 3D shape model representing **articulation** and **shape variation** across different species



Examples from the training set

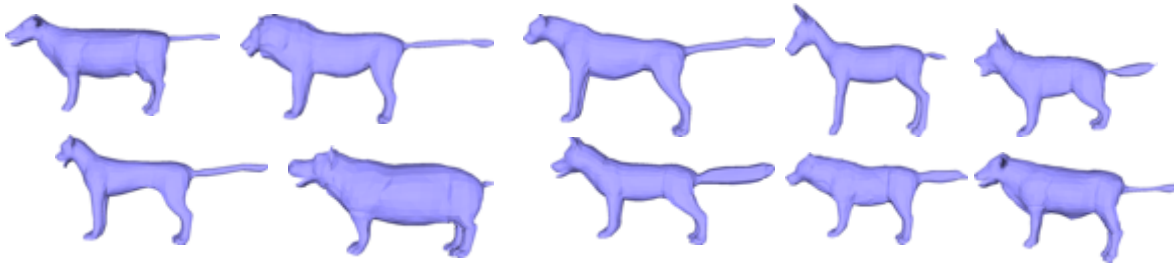


- **From 3D data**, fast to compute

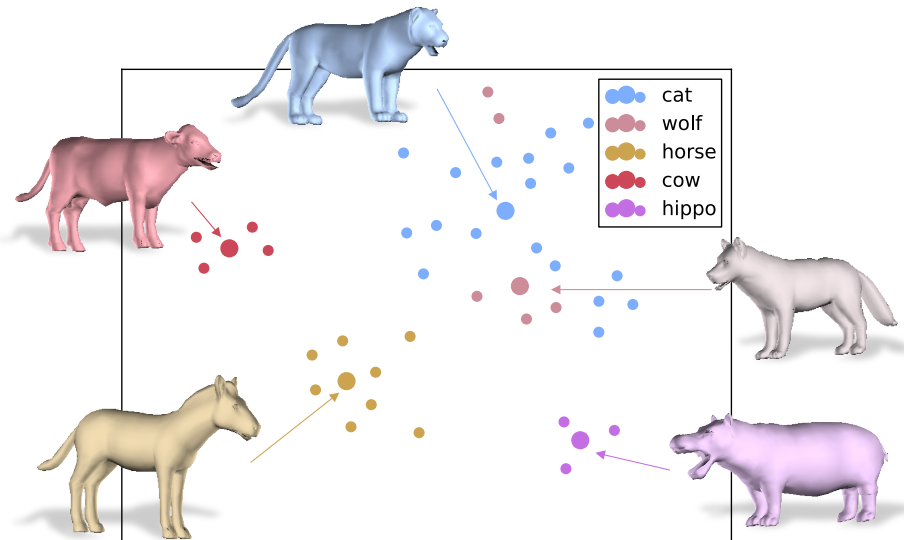
S. Zuffi, A. Kanazawa, D. Jacobs, M. J. Black, 3D Menagerie: Modeling the 3D Shape and Pose of Animals, CVPR 2017

SMAL shape space

Training set: Toys scans in correspondence and in reference pose

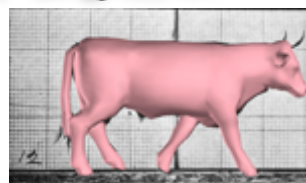
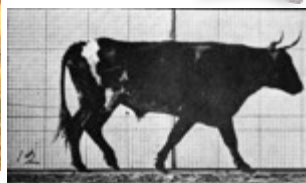
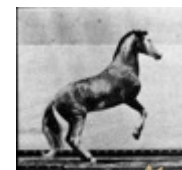
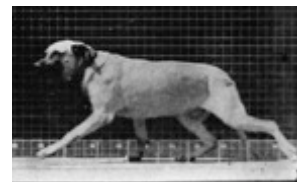


$$\mathbf{v}_{shape}(\beta) = \mathbf{v}_{template} + B_s \beta$$



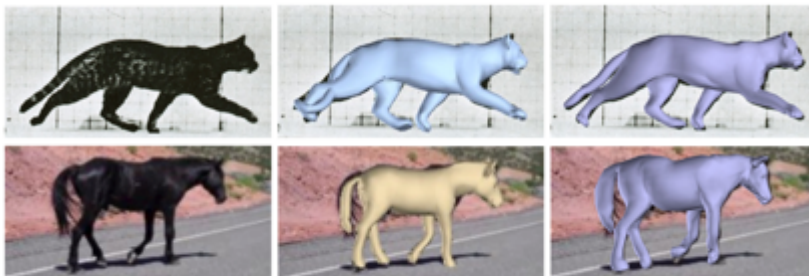
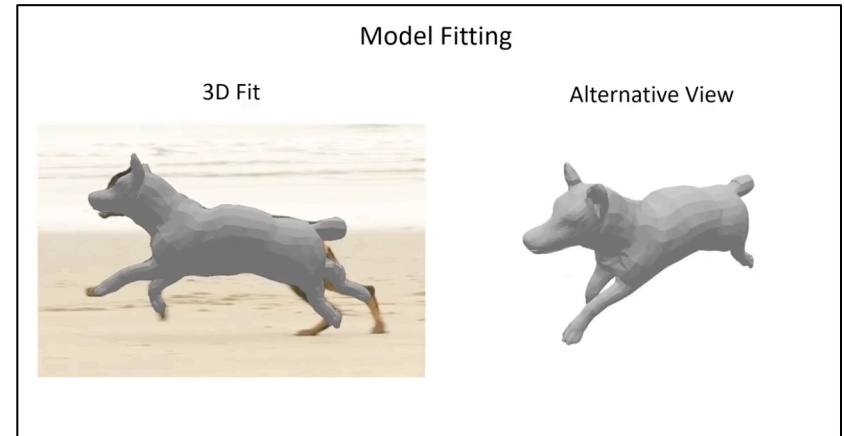
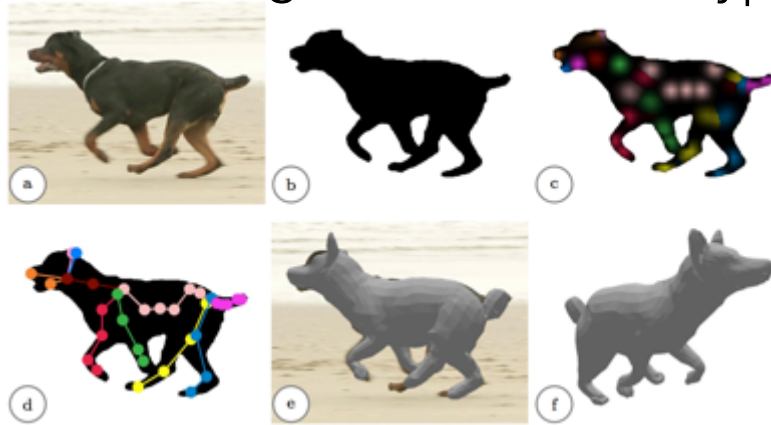
Applications of SMAL

Manual segmentation and manually annotated keypoints



Applications of SMAL

Automatic segmentation and keypoints detection from silhouette



RGB

SMAL [9]

Ours

B. Biggs, T. Roddick, A. Fitzgibbon, R. Cipolla, Creatures great and SMAL: Recovering the shape and motion of animals from video, ACCV2019

Our work

- **GOAL:** Estimate 3D shape and pose as a direct regression from RGB
- **APPROACH:** Supervised, training based only on synthetic data

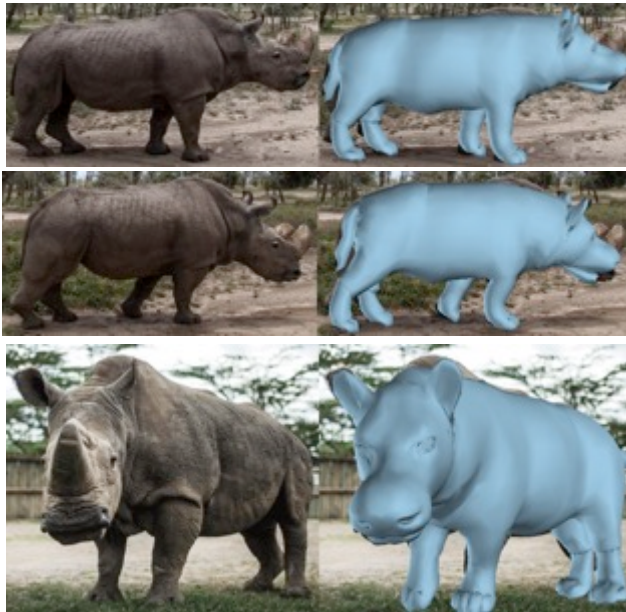




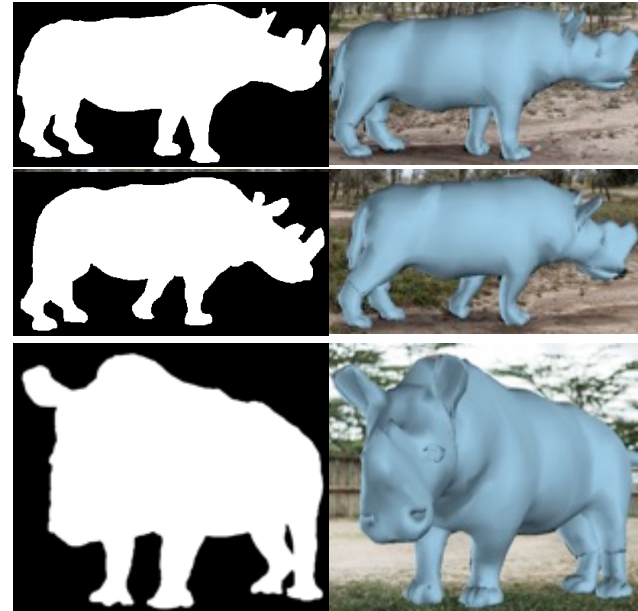
SMAL with Refinement (SMALR)



1. SMAL model fitting



2. Model-free shape Refinement



S. Zuffi, A. Kanazawa, M. J. Black, Lions and Tigers and Bears:
Capturing Non-Rigid, 3D, Articulated Shape from Images, CVPR2018



Animals avatars with SMALR



S. Zuffi, A. Kanazawa, M. J. Black, Lions and Tigers and Bears:
Capturing Non-Rigid, 3D, Articulated Shape from Images, CVPR2018

Grevy's zebra avatars

Multiple images of the same subject



3D model



Texture map

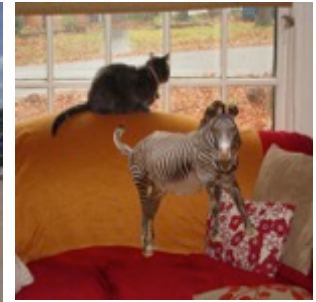
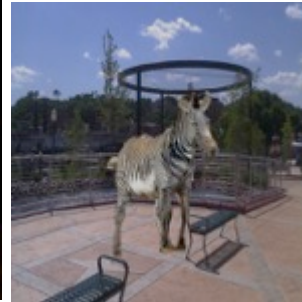
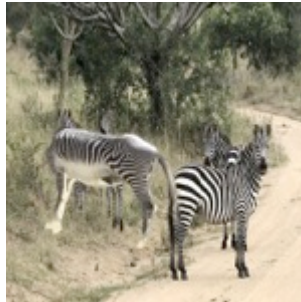
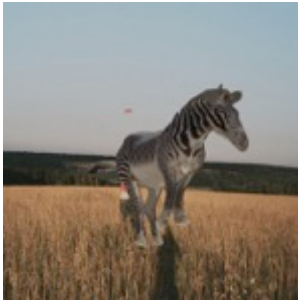




Synthetic dataset from avatars



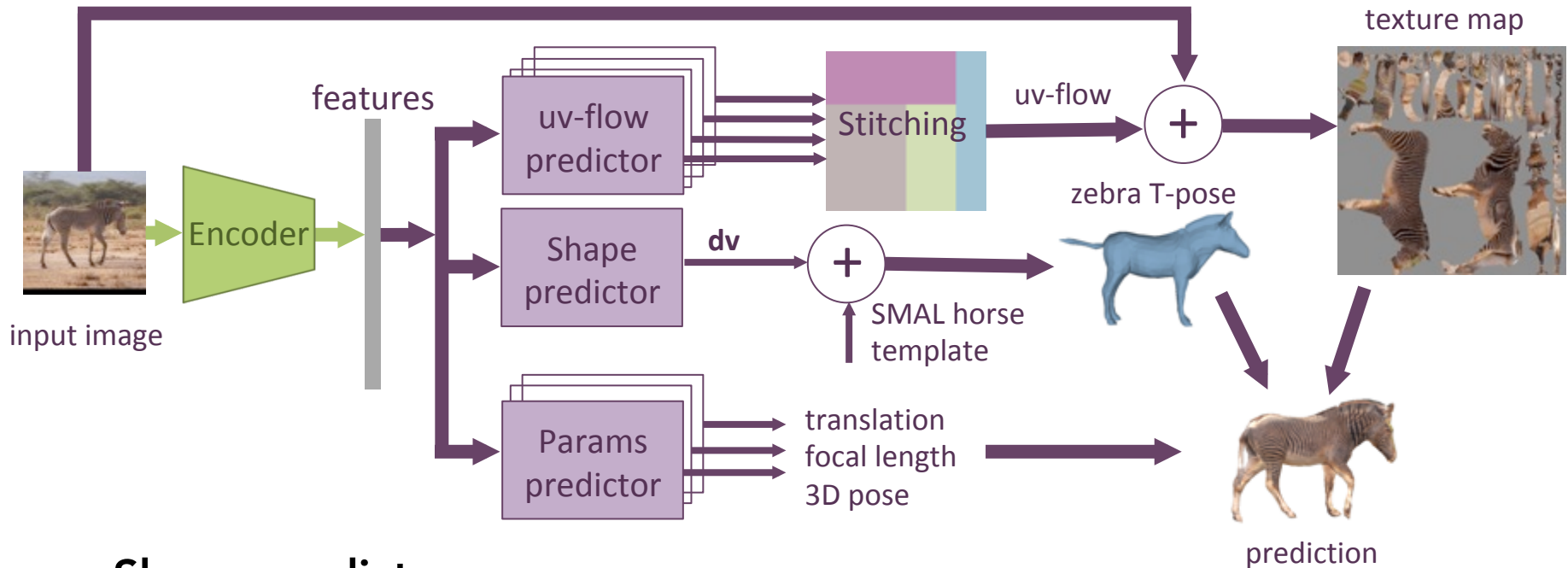
Synthetic



Real



Network



Shape predictor:

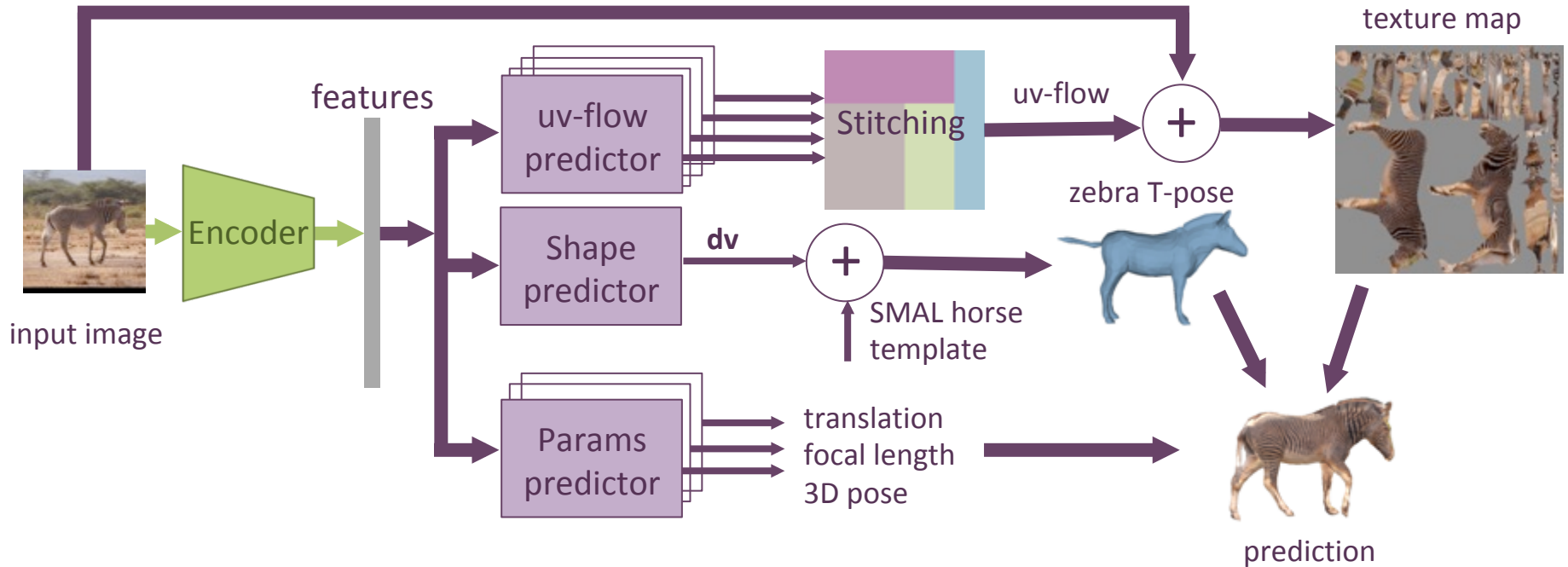
$$\mathbf{v}_{shape}(f_s) = \mathbf{v}_{template} + \mathbf{dv}$$

$$\mathbf{dv} = W f_s + b$$

SMAL model:

$$\mathbf{v}_{shape}(\beta) = \mathbf{v}_{template} + B_s \beta$$

Network

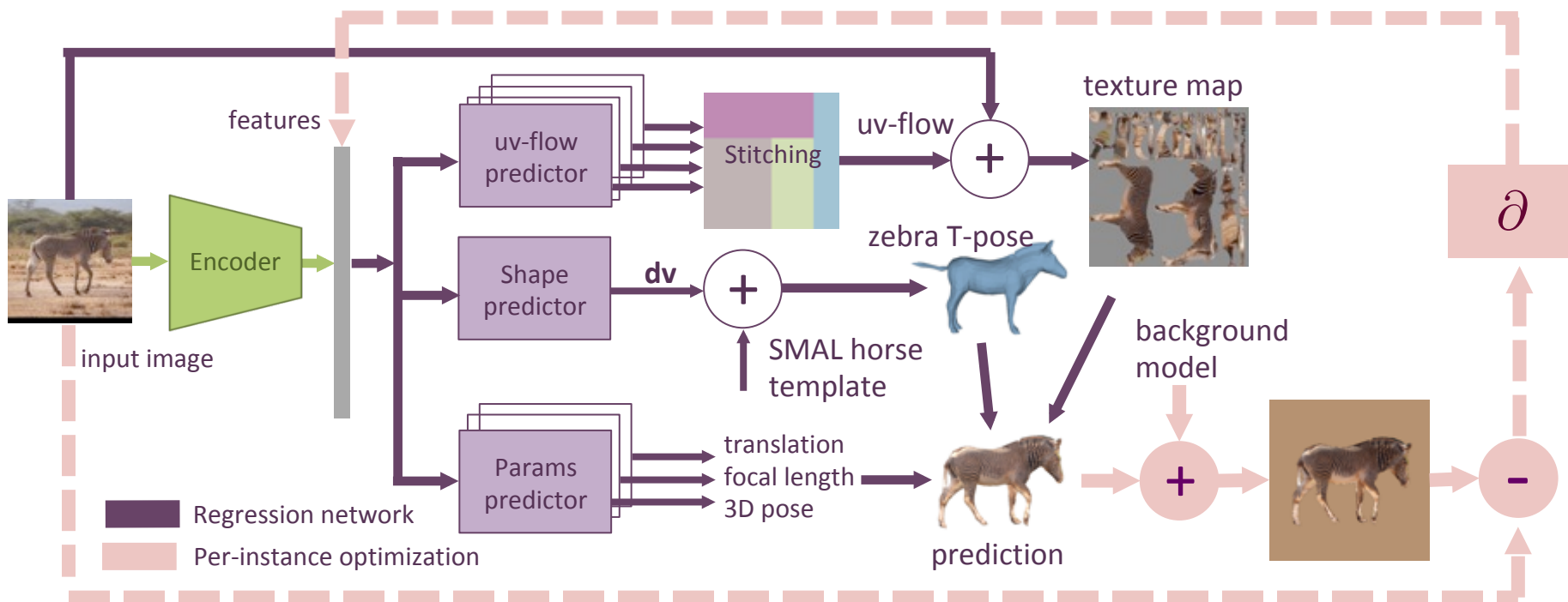


$$\begin{aligned}
 L_{train} = & L_{mask}(S_{gt}, S) + L_{kp_{2D}}(K_{2D,gt}, K_{2D}) + \\
 & L_{cam}(f_{gt}, f) + L_{img}(I_{input}, I, S_{gt}) + L_{pose}(\theta_{gt}, \theta) + \\
 & L_{trans}(\gamma_{gt}, \gamma) + L_{shape}(\mathbf{dv}_{gt}, \mathbf{dv}) + L_{uv}(\mathbf{uv}_{gt}, \mathbf{uv}) + \\
 & L_{tex}(T_{gt}, T) + L_{dt}(\mathbf{uv}, S_{gt})
 \end{aligned}$$

Results on test set

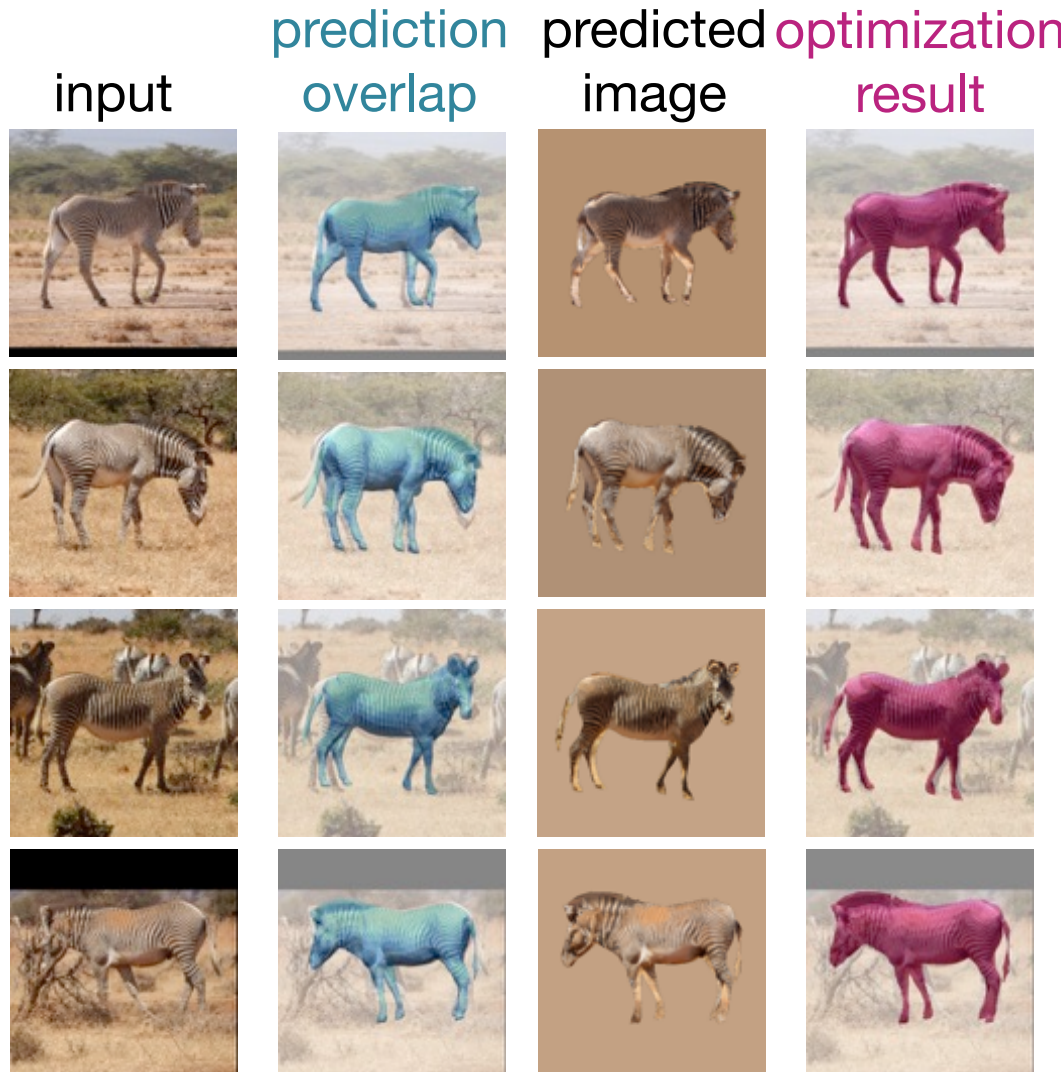


Unsupervised optimization



$$L_{opt} = L_{photo}(I_{input}, I) + L_{cam}(\hat{f}, f) + L_{trans}(\hat{\gamma}, \gamma)$$

Unsupervised optimization



Results

| Method | PCK@0.05 | PCK@0.1 | IoU |
|-------------------------------|-------------|-------------|--------------|
| (A) SMAL (gt kp and seg) | 92.2 | 99.4 | 0.463 |
| (B) feed-forward on synthetic | 80.4 | 97.1 | 0.423 |
| (C) opt features | 62.3 | 81.6 | 0.422 |
| (D) opt variables | 59.2 | 80.6 | 0.418 |
| (E) opt features bg img | 59.7 | 80.5 | 0.416 |
| (F) feed-forward pred. | 59.5 | 80.3 | 0.416 |
| (G) no texture | 52.3 | 76.2 | 0.401 |
| (H) noise bbox | 58.7 | 79.9 | 0.415 |

Texture
prediction
helps!

Better to
optimize over
features



Poster n.93, 31st Oct 10:30



S. Zuffi, A. Kanazawa, T. Berger-Wolf, M.J. Black, 3D Safari: Learning to Estimate Zebra Pose, Shape, and Texture from Images "In the Wild", ICCV 2019